



▶ **Stealth[®] MultiDrive[™] Series:** **The Flexible Right Angle**

Stealth[®] MultiDrive[™] (MD) offers three different output options for true flexibility. MultiDrive models include Low Ratio, Dual Shaft and Hollow Shaft options in a compact, right angle package. With 5 frame sizes and multiple ratios to choose from, you are guaranteed to find a Stealth[®] MultiDrive to fit your servo motor application.

MultiDrive[™] features Stealth[®] helical gearing for high torque, high accuracy and quiet operation in a compact, right angle package.

- **Low Backlash**
Standard as low as 8 arc minutes and 4 arc minutes optional
- **Space Saving**
compact, right angle design saves space in many applications
- **Smooth, Quiet Operation and Long Life**
hardened, precision spiral bevel gears ensure quiet operation.
- **Quick, Error-Free Mounting**
to any servo or stepper motor using Bayside's patented ServoMount[®] design.
- **Sealed Unit...**
seals and o-rings provide IP65 protection to prevent leaks and to protect against harsh environments.



**RT Model
Hollow Shaft**

Hollow Shaft Model

5 Frame Sizes

| |
|-------|
| RT90 |
| RT115 |
| RT142 |
| RT180 |
| RT220 |

Ratios

| |
|------|
| 3:1 |
| 9:1 |
| 15:1 |
| 21:1 |
| 30:1 |



Dual Shaft Model

5 Frame Sizes

RD90

RD115

RD142

RD180

RD220

Ratios

1:1 15:1

2:1 21:1

3:1 30:1

9:1

**RD Model
Dual Shaft**



**RB Model
Low Ratio**



Low Ratio Model

5 Frame Sizes

RB90

RB115

RB142

RB180

RB220

Ratios

1:1

2:1

3:1



Stealth[®] MultiDrive Series:

Performance Specifications

| | Units | Ratio | Frame Size (RT, RD, RB) | | | | |
|---|-----------------|------------|-------------------------|-------|-------|-------|-------|
| | | | R_90 | R_115 | R_142 | R_180 | R_220 |
| Nominal Output Torque, $T_{nom r}$ | Nm | 1 | 23 | 45 | 113 | 192 | 508 |
| | in lb | | 200 | 400 | 1,000 | 1,700 | 4,500 |
| Max. Acceleration Output Torque, $T_{acc r}$ | Nm | 2-30 | 34 | 90 | 136 | 260 | 565 |
| | in lb | | 300 | 800 | 1,200 | 2,300 | 5,000 |
| Emergency ⁽¹⁾ Stop Output Torque, $T_{em r}$ | Nm | 1 | 28 | 56 | 141 | 240 | 636 |
| | in lb | | 250 | 500 | 1,250 | 2,125 | 5,625 |
| | Nm | 2-30 | 42 | 113 | 169 | 324 | 636 |
| | in lb | | 375 | 1,000 | 1,500 | 2,875 | 5,625 |
| Nominal Input Speed, $N_{nom r}$ | RPM | 1,2,3 | 3,000 | 2,600 | 2,200 | 1,800 | 1,400 |
| | RPM | 9,15,21,30 | 3,800 | 3,400 | 3,000 | 2,400 | 1,800 |
| Max. Input Speed, $N_{max r}$ | RPM | 1,2,3 | 4,000 | 3,500 | 2,900 | 2,500 | 1,600 |
| | RPM | 9,15,21,30 | 5,300 | 4,500 | 3,800 | 3,000 | 2,300 |
| Standard Backlash | arc min | 1,2,3 | 10 | 9 | 9 | 8 | 8 |
| | arc min | 9,15,21,30 | 12 | 11 | 11 | 10 | 10 |
| Low Backlash | arc min | 1,2,3 | 6 | 5 | 5 | 4 | 4 |
| | arc min | 9,15,21,30 | 8 | 7 | 7 | 6 | 6 |
| Efficiency at Nominal Torque | % | 1,2,3 | 95 | 95 | 95 | 95 | 95 |
| | % | 9,15,21,30 | 92 | 92 | 92 | 92 | 92 |
| Noise Level ⁽²⁾ at: 2,500 RPM | dB | All | 70 | 70 | 70 | — | — |
| | dB | | — | — | — | 72 | 72 |
| Torsional Stiffness | Nm / arc min | All | 3 | 6 | 16 | 43 | 90 |
| | in lb / arc min | | 28 | 56 | 140 | 380 | 800 |
| Maximum Weight | kg | All | 7 | 13 | 25 | 54 | 114 |
| | lb | | 16 | 28 | 56 | 120 | 250 |
| Maximum Allowable Case Temperature | °C | All | ←————— 100 —————→ | | | | |

| Specifications: | Units | Ratio | Frame Size (RT, RD, RB) | | | | |
|----------------------------------|------------------------|---------|-------------------------|-------|-------|-------|-------|
| | | | R_90 | R_115 | R_142 | R_180 | R_220 |
| Moment of Inertia ⁽³⁾ | gm cm sec ² | 1 | 3.28 | 11.0 | 38.7 | 101 | 444 |
| | oz in sec ² | | 0.046 | 0.153 | 0.538 | 1.41 | 6.17 |
| | gm cm sec ² | 2 | 4.17 | 11.3 | 32.8 | 95.4 | 274 |
| | oz in sec ² | | 0.058 | 0.157 | 0.455 | 1.32 | 3.81 |
| | gm cm sec ² | 3 | 2.68 | 7.75 | 22.3 | 65.6 | 191 |
| | oz in sec ² | | 0.037 | 0.108 | 0.311 | 0.911 | 2.65 |
| | gm cm sec ² | 9 | 1.07 | 3.28 | 10.4 | 35.8 | 119 |
| | oz in sec ² | | 0.015 | 0.046 | 0.145 | 0.497 | 1.66 |
| | gm cm sec ² | 15 - 30 | 0.566 | 2.09 | 5.36 | 17.9 | 62.6 |
| | oz in sec ² | | 0.008 | 0.029 | 0.075 | 0.248 | 0.869 |

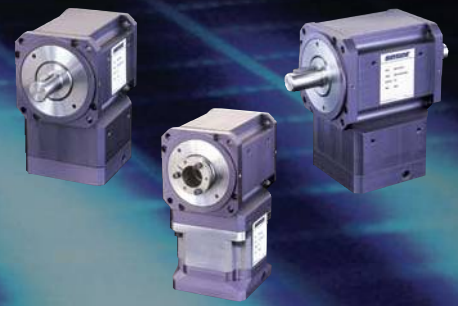
(1) Maximum of 1,000 stops

(2) Measured at 1 meter

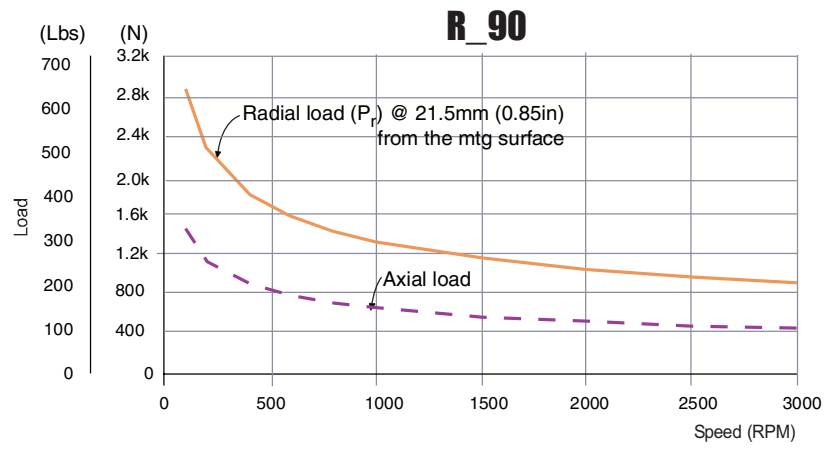
(3) All Moment of Inertia values are as reflected at the input shaft of the gearhead.

Specification are subject to change without notice

Stealth® MultiDrive Series: Output Shaft Load Rating

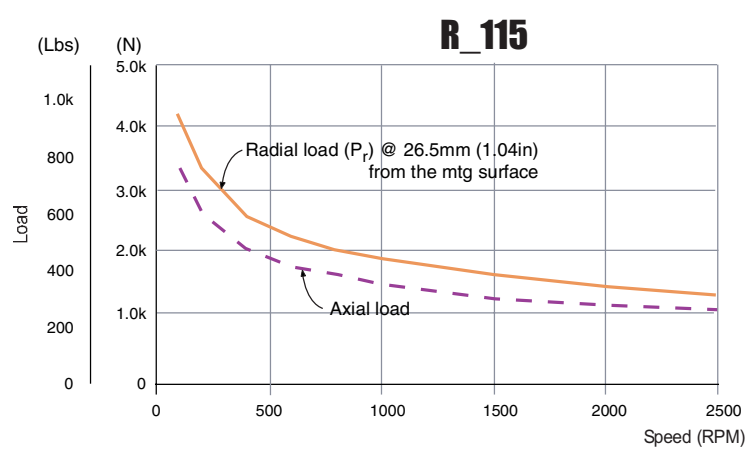


Formulas to calculate Radial Load (P_{rx}) at any distance "X" from the gearhead mounting surface.



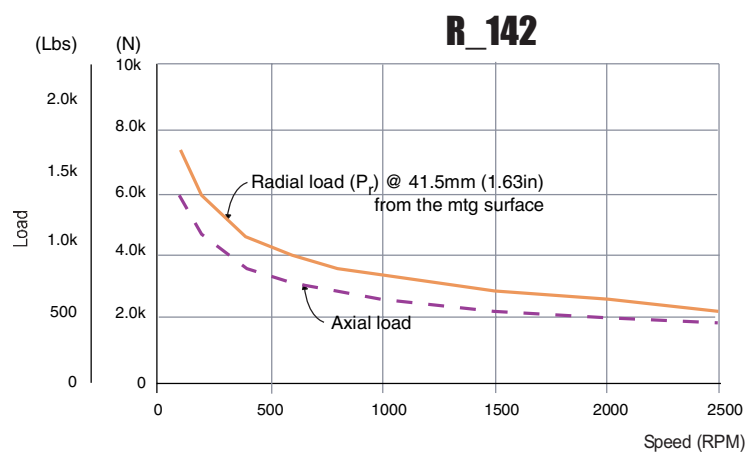
$$P_{rx} = (P_r)(121\text{mm}) / (100\text{mm} + X)$$

$$P_{rx} = (P_r)(4.76\text{in}) / (3.94\text{in} + X)$$



$$P_{rx} = (P_r)(151\text{mm}) / (125\text{mm} + X)$$

$$P_{rx} = (P_r)(5.94\text{in}) / (4.92\text{in} + X)$$



$$P_{rx} = (P_r)(201\text{mm}) / (160\text{mm} + X)$$

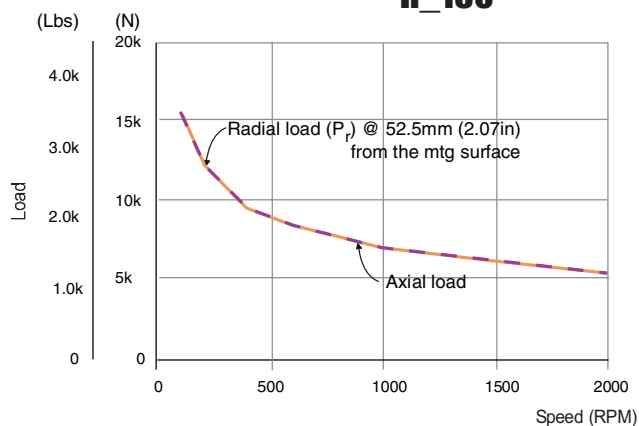
$$P_{rx} = (P_r)(7.91\text{in}) / (6.30\text{in} + X)$$



Stealth® MultiDrive Series: Output Shaft Load Rating

Formulas to calculate Radial Load (P_{rx}) at any distance "X" from the gearhead mounting surface.

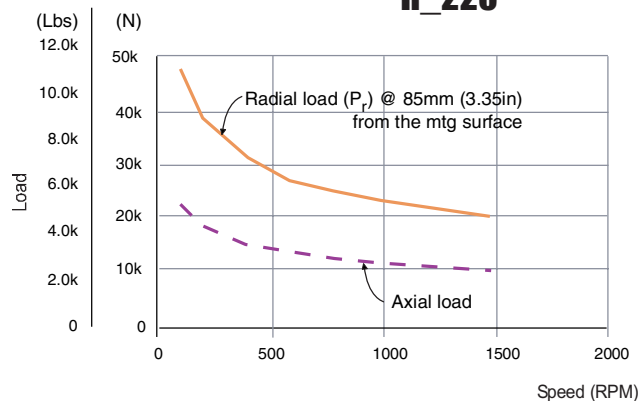
R_180



$$P_{rx} = (P_r)(260\text{mm}) / (208\text{mm} + X)$$

$$P_{rx} = (P_r)(10.24\text{in}) / (8.19\text{in} + X)$$

R_220



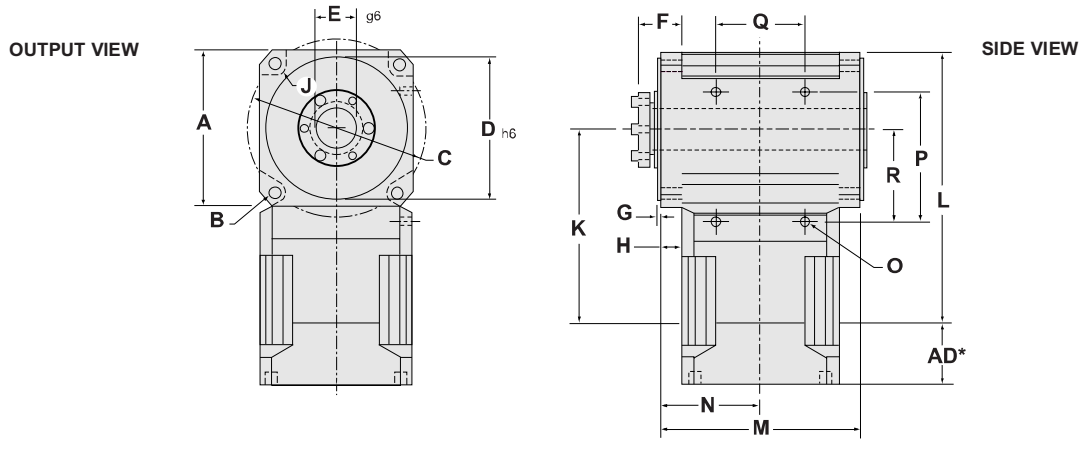
$$P_{rx} = (P_r)(352\text{mm}) / (267\text{mm} + X)$$

$$P_{rx} = (P_r)(13.86\text{in}) / (10.5\text{in} + X)$$

Stealth® MultiDrive Series: RT Hollow Shaft



Dimensions



| Frame Size | A Square Flange | | B Bolt Hole | | C Bolt Circle | | D Pilot Diameter | | E Thru Bore Diameter** | | F Taper Bushing Extension | | G Pilot Thickness | | H Flange Thickness | |
|------------|-----------------|-------|-------------|-------|---------------|-------|------------------|-------|------------------------|-------|---------------------------|-------|-------------------|-------|--------------------|-------|
| | (mm) | (in) | (mm) | (in) | (mm) | (in) | (mm) | (in) | (mm) | (in) | (mm) | (in) | (mm) | (in) | (mm) | (in) |
| RT90 | 90 | 3.543 | 6.5 | 0.256 | 100 | 3.937 | 80 | 3.150 | 22 | 0.866 | 26.5 | 1.043 | 3 | 0.118 | 12 | 0.472 |
| RT115 | 115 | 4.528 | 8.5 | 0.335 | 130 | 5.118 | 110 | 4.331 | 30 | 1.181 | 31 | 1.220 | 3.5 | 0.138 | 14 | 0.551 |
| RT142 | 142 | 5.591 | 11 | 0.433 | 165 | 6.496 | 130 | 5.118 | 38 | 1.496 | 43 | 1.693 | 3.5 | 0.138 | 20 | 0.787 |
| RT180 | 182 | 7.165 | 13 | 0.512 | 215 | 8.465 | 160 | 6.299 | 48 | 1.890 | 54.2 | 2.134 | 10 | 0.394 | 25 | 0.984 |
| RT220 | 220 | 8.661 | 17 | 0.669 | 250 | 9.843 | 180 | 7.087 | 60 | 2.362 | 74.1 | 2.917 | 15 | 0.591 | 35 | 1.378 |

| Frame Size | J Housing Recess | | K Dist. to Output Centerline (For ratio = 3:1) | | K2 Dist. to Output Centerline (For ratio > 3:1) | | L1 Housing Length (For ratio = 3:1) | | L2 Housing Length (For ratio > 3:1) | | M Housing Width | | N Dist. to Input Centerline | |
|------------|------------------|-------|--|-------|---|--------|-------------------------------------|--------|-------------------------------------|--------|-----------------|--------|-----------------------------|-------|
| | (mm) | (in) | (mm) | (in) | (mm) | (in) | (mm) | (in) | (mm) | (in) | (mm) | (in) | (mm) | (in) |
| RT90 | 6.6 | 0.260 | 95 | 3.740 | 117 | 4.606 | 140 | 5.512 | 162 | 6.378 | 114 | 4.488 | 57 | 2.244 |
| RT115 | 7.9 | 0.311 | 116 | 4.567 | 144.2 | 5.677 | 173.5 | 6.831 | 201.7 | 7.941 | 143 | 5.630 | 71.5 | 2.815 |
| RT142 | 10.5 | 0.413 | 134 | 5.276 | 179 | 7.047 | 205 | 8.071 | 250 | 9.843 | 182 | 7.165 | 91 | 3.583 |
| RT180 | 10 | 0.394 | 169 | 6.654 | 209.1 | 8.228 | 260 | 10.236 | 300.1 | 11.815 | 232 | 9.134 | 116 | 4.567 |
| RT220 | 16 | 0.630 | 206 | 8.110 | 266 | 10.472 | 316 | 12.441 | 376 | 14.803 | 290 | 11.417 | 145 | 5.709 |

Both output flanges have identical dimensions.
 *AD=Adapter Length. Adapter will vary, depending on motor. Consult Internet (www.baysidemotion.com) for details or call Bayside.
 **Maximum bushing bore diameter. Actual through bore of output shaft is larger. For additional bore diameter, contact Bayside's Application Engineers for information.

| Frame Size | O Thread Size x Depth | P | | Q | | R | |
|------------|-----------------------|------|-------|------|-------|------|-------|
| | | (mm) | (in) | (mm) | (in) | (mm) | (in) |
| R_90 | M4x6 | 80 | 3.150 | 60 | 2.362 | 60 | 2.362 |
| R_115 | M6x9 | 100 | 3.937 | 70 | 2.756 | 75 | 2.953 |
| R_142 | M8x12 | 120 | 4.724 | 80 | 3.150 | 85 | 3.346 |
| R_180 | M10x15 | 160 | 6.299 | 100 | 3.937 | 110 | 4.331 |
| R_220 | M12x20 | 195 | 7.677 | 130 | 5.118 | 136 | 5.354 |

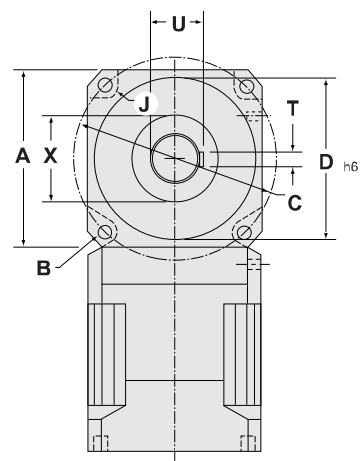
Gearmotors & Gearheads



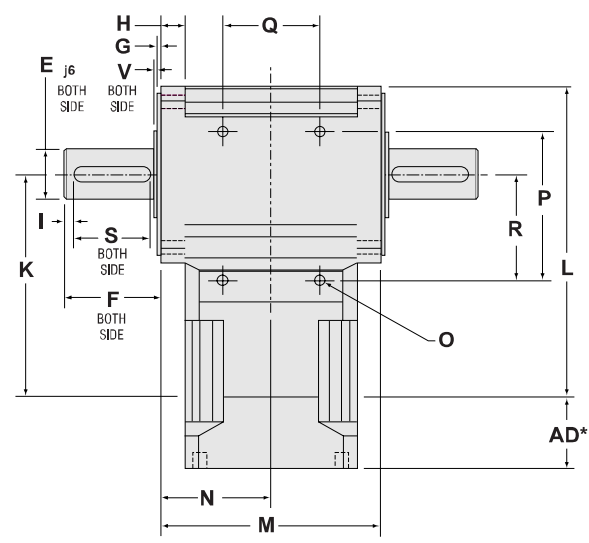
Stealth® MultiDrive Series: RD Dual Shaft

Dimensions

OUTPUT VIEW



SIDE VIEW



| Frame Size | A Square Flange | | B Bolt Hole | | C Bolt Circle | | D Pilot Diameter | | E Output Shaft Diameter | | F Output Shaft Length | | G Pilot Thickness | | H Flange Thickness | | I Dist. From Shaft End | | J Housing Recess | |
|------------|-----------------|-------|-------------|-------|---------------|-------|------------------|-------|-------------------------|-------|-----------------------|-------|-------------------|-------|--------------------|-------|------------------------|-------|------------------|-------|
| | (mm) | (in) | (mm) | (in) | (mm) | (in) | (mm) | (in) | (mm) | (in) | (mm) | (in) | (mm) | (in) | (mm) | (in) | (mm) | (in) | (mm) | (in) |
| RD90 | 90 | 3.543 | 6.5 | 0.256 | 100 | 3.937 | 80 | 3.150 | 20 | 0.787 | 40 | 1.575 | 3 | 0.118 | 12 | 0.472 | 5 | 0.197 | 6.6 | 0.260 |
| RD115 | 115 | 4.528 | 8.5 | 0.335 | 130 | 5.118 | 110 | 4.331 | 24 | 0.945 | 50 | 1.969 | 3.5 | 0.138 | 14 | 0.551 | 7 | 0.276 | 7.9 | 0.311 |
| RD142 | 142 | 5.591 | 11 | 0.433 | 165 | 6.496 | 130 | 5.118 | 40 | 1.575 | 80 | 3.150 | 3.5 | 0.138 | 20 | 0.787 | 8 | 0.315 | 10.5 | 0.413 |
| RD180 | 182 | 7.165 | 13 | 0.512 | 215 | 8.465 | 160 | 6.299 | 50 | 1.969 | 95 | 3.740 | 10 | 0.394 | 25 | 0.984 | 6 | 0.236 | 10 | 0.394 |
| RD220 | 220 | 8.661 | 17 | 0.669 | 250 | 9.843 | 180 | 7.087 | 75 | 2.953 | 155 | 6.102 | 15 | 0.591 | 35 | 1.378 | 8 | 0.315 | 16 | 0.630 |

| Frame Size | K1 Dist. to Output Centerline (For ratio <= 3:1) | | K2 Dist. to Output Centerline (For ratio > 3:1) | | L1 Housing Length (For ratio <= 3:1) | | L2 Housing Length (For ratio > 3:1) | | M Housing Width | | N Dist. to Input Centerline | | S Keyway Length | | T Keyway Thickness | | U Keyway Height | | V Shoulder Height | | X Shoulder Diameter | |
|------------|--|-------|---|--------|--------------------------------------|--------|-------------------------------------|--------|-----------------|--------|-----------------------------|-------|-----------------|-------|--------------------|-------|-----------------|-------|-------------------|-------|---------------------|-------|
| | (mm) | (in) | (mm) | (in) | (mm) | (in) | (mm) | (in) | (mm) | (in) | (mm) | (in) | (mm) | (in) | (mm) | (in) | (mm) | (in) | (mm) | (in) | (mm) | (in) |
| RD90 | 95 | 3.740 | 117 | 4.606 | 140 | 5.512 | 162 | 6.378 | 114 | 4.488 | 57 | 2.244 | 28 | 1.102 | 6 | 0.236 | 22.5 | 0.886 | 2.5 | 0.098 | 45 | 1.575 |
| RD115 | 116 | 4.567 | 144.2 | 5.677 | 173.5 | 6.831 | 201.7 | 7.941 | 143 | 5.630 | 71.5 | 2.815 | 32 | 1.260 | 8 | 0.315 | 27 | 1.063 | 2.5 | 0.098 | 50 | 1.969 |
| RD142 | 134 | 5.276 | 179 | 7.047 | 205 | 8.071 | 250 | 9.843 | 182 | 7.165 | 91 | 3.583 | 63 | 2.480 | 12 | 0.472 | 43 | 1.693 | 2.5 | 0.098 | 50 | 1.969 |
| RD180 | 169 | 6.654 | 209.1 | 8.232 | 260 | 10.236 | 300.1 | 11.815 | 232 | 9.134 | 116 | 4.567 | 70 | 2.756 | 14 | 0.551 | 53.5 | 2.106 | 2.5 | 0.098 | 55 | 2.165 |
| RD220 | 206 | 8.110 | 266 | 10.472 | 316 | 12.441 | 376 | 14.803 | 290 | 11.417 | 145 | 5.709 | 100 | 3.937 | 20 | 0.787 | 79.5 | 3.130 | 2.5 | 0.098 | 100 | 3.937 |

Both output flanges have identical dimensions. Contact Bayside's Application Engineers for information.
 *AD=Adapter Length. Adapter will vary, depending on motor. Consult Internet (www.baysidemotion.com) for details or call Bayside.

| Encoder Mounting Option | Dimensions For All Frame Sizes | |
|-------------------------|--------------------------------|-------|
| | (mm) | (in) |
| Shaft Diameter | 9.525 | 0.375 |
| Shaft Length | 19.050 | 0.750 |
| Bolt Circle | 74.981 | 2.952 |
| Tapped Holes | M4x6 (Min. Depth) | |
| Encoder (Not Supplied) | DRC C25, BEI E25, RENCO C2520 | |

An additional flange is required on the gearhead for encoder mounting. It will increase the thickness of one output flange by 10mm.

| Frame Size | Foot Mounting Holes Location (RT, RD, RB) | | | | | | | |
|------------|---|------|-------|------|-------|------|-------|--|
| | 0 Thread Size x Depth | P | | Q | | R | | |
| | | (mm) | (in) | (mm) | (in) | (mm) | (in) | |
| R_90 | M4x6 | 80 | 3.150 | 60 | 2.362 | 60 | 2.362 | |
| R_115 | M6x9 | 100 | 3.937 | 70 | 2.756 | 75 | 2.953 | |
| R_142 | M8x12 | 120 | 4.724 | 80 | 3.150 | 85 | 3.346 | |
| R_180 | M10x15 | 160 | 6.299 | 100 | 3.937 | 110 | 4.331 | |
| R_220 | M12x20 | 195 | 7.677 | 130 | 5.118 | 136 | 5.354 | |

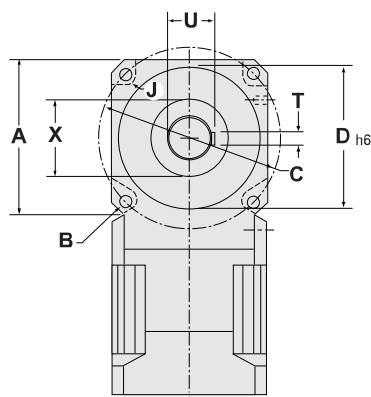
Stealth® MultiDrive Series:

RB Low Ratio

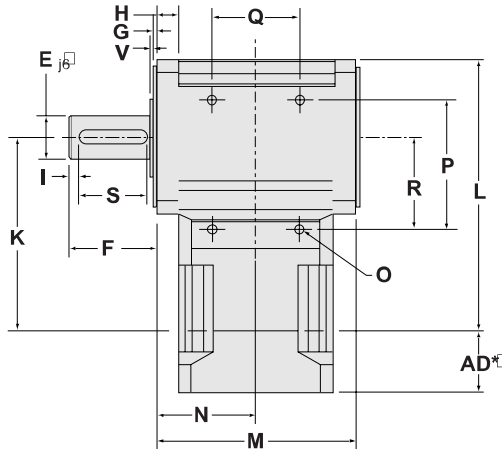


Dimensions

OUTPUT VIEW



SIDE VIEW



| Frame Size | A Square Flange | | B Bolt Hole | | C Bolt Circle | | D Pilot Diameter | | E Output Shaft Diameter | | F Output Shaft Length | | G Pilot Thickness | | H Flange Thickness | | I Dist. From Shaft End | | J Housing Recess | |
|------------|-----------------|-------|-------------|-------|---------------|-------|------------------|-------|-------------------------|-------|-----------------------|-------|-------------------|-------|--------------------|-------|------------------------|-------|------------------|-------|
| | (mm) | (in) | (mm) | (in) | (mm) | (in) | (mm) | (in) | (mm) | (in) | (mm) | (in) | (mm) | (in) | (mm) | (in) | (mm) | (in) | (mm) | (in) |
| RB90 | 90 | 3.543 | 6.5 | 0.256 | 100 | 3.937 | 80 | 3.150 | 20 | 0.787 | 40 | 1.575 | 3 | 0.118 | 12 | 0.472 | 5 | 0.197 | 6.6 | 0.260 |
| RB115 | 115 | 4.528 | 8.5 | 0.335 | 130 | 5.118 | 110 | 4.331 | 24 | 0.945 | 50 | 1.969 | 3.5 | 0.138 | 14 | 0.551 | 7 | 0.276 | 7.9 | 0.311 |
| RB142 | 142 | 5.591 | 11 | 0.433 | 165 | 6.496 | 130 | 5.118 | 40 | 1.575 | 80 | 3.150 | 3.5 | 0.138 | 20 | 0.787 | 8 | 0.315 | 10.5 | 0.413 |
| RB180 | 182 | 7.165 | 13 | 0.512 | 215 | 8.465 | 160 | 6.299 | 50 | 1.969 | 95 | 3.740 | 10 | 0.394 | 25 | 0.984 | 6 | 0.236 | 10.0 | 0.394 |
| RB220 | 220 | 8.661 | 17 | 0.669 | 250 | 9.843 | 180 | 7.087 | 75 | 2.953 | 155 | 6.102 | 15 | 0.591 | 35 | 1.378 | 8 | 0.315 | 16.0 | 0.630 |

| Frame Size | K Dist. to Output Centerline | | L Housing Length | | M Housing Width | | N Dist. to Input Centerline | | S Keyway Length | | T Keyway Thickness | | U Keyway Height | | V Shoulder Height | | X Shoulder Diameter | |
|------------|------------------------------|-------|------------------|--------|-----------------|--------|-----------------------------|-------|-----------------|-------|--------------------|-------|-----------------|-------|-------------------|-------|---------------------|-------|
| | (mm) | (in) | (mm) | (in) | (mm) | (in) | (mm) | (in) | (mm) | (in) | (mm) | (in) | (mm) | (in) | (mm) | (in) | (mm) | (in) |
| RB90 | 95 | 3.740 | 140.6 | 5.512 | 114 | 4.488 | 57 | 2.244 | 28 | 1.102 | 6 | 0.236 | 22.5 | 0.886 | 2.5 | 0.098 | 45 | 1.575 |
| RB115 | 116 | 4.567 | 173.5 | 6.831 | 143 | 5.630 | 71.5 | 2.815 | 32 | 1.260 | 8 | 0.315 | 27 | 1.063 | 2.5 | 0.098 | 50 | 1.969 |
| RB142 | 134 | 5.276 | 205 | 8.071 | 182 | 7.165 | 91 | 3.583 | 63 | 2.480 | 12 | 0.472 | 43 | 1.693 | 2.5 | 0.098 | 50 | 1.969 |
| RB180 | 169 | 6.654 | 260 | 10.236 | 232 | 9.134 | 116 | 4.567 | 70 | 2.756 | 14 | 0.551 | 53.5 | 2.106 | 2.5 | 0.098 | 55 | 2.165 |
| RB220 | 206 | 8.110 | 316 | 12.441 | 290 | 11.417 | 145 | 5.709 | 100 | 3.937 | 20 | 0.787 | 79.5 | 3.130 | 2.5 | 0.098 | 100 | 3.937 |

Both output flanges have identical dimensions.

*AD=Adapter Length. Adapter will vary, depending on motor. Consult Internet (www.baysidemotion.com) for details or call Bayside.

*Additional hollow shaft bore diameters are available. Contact Bayside's Application Engineers for information.

Specifications are subject to change without notice.

How to Order

Order Numbering Example:



| MODEL | FRAME SIZE | OPTIONAL | RATIOS | SPECIAL | OPTIONAL |
|------------------|------------|----------|-----------|---------|--------------|
| RB= Low Ratio | 090 | ENCODER | RB RD | RI | LOW BACKLASH |
| RD= Dual-Shaft | 115 | MOUNT | 001 001 | - | |
| RT= Hollow Shaft | 142 | RD Only | 002 002 | - | |
| | 180 | | 003 003 | | |
| | 220 | | - 009 009 | | |
| | | | - 015 015 | | |
| | | | - 021 021 | | |
| | | | - 030 030 | | |

1. Pick frame size and ratio.
2. Pick options.
3. Specify motor make and model for mounting kit.

MultiDrive Gearheads are supported by a worldwide network of offices and local distributors. Call **1-800-305-4555** for application engineering assistance or for the name of your local distributor. Information can also be obtained at www.baysidemotion.com.

Stealth[®] RS Advanced Series

Performance Specifications

| | Units | Ratio | Frame Size | | | | | | |
|--|-----------------|--------|------------|-------|-------|-------|--------|--------|---------|
| | | | RS60 | RS90 | RS115 | RS142 | RS180 | RS220 | RS300 |
| Nominal Output Torque, $T_{nom r}$ | Nm | 5 | 11 | 28 | 75 | 141 | 316 | 678 | 2,203 |
| | in lb | | 95 | 250 | 660 | 1,250 | 2,800 | 6,000 | 19,500 |
| | Nm | 10 | 21 | 55 | 147 | 271 | 621 | 1,299 | 2,712 |
| | in lb | | 190 | 490 | 1,300 | 2,400 | 5,500 | 11,500 | 24,000 |
| | Nm | 15-25 | 33 | 85 | 215 | 395 | 938 | 1,808 | 4,181 |
| | in lb | | 290 | 750 | 1,900 | 3,500 | 8,300 | 16,000 | 37,000 |
| Max. Acceleration Output Torque, $T_{acc r}$ | Nm | 30-100 | 28 | 85 | 192 | 316 | 836 | 1,469 | 4,181 |
| | in lb | | 250 | 750 | 1,700 | 2,800 | 7,400 | 13,000 | 37,000 |
| | Nm | 5 | 13 | 33 | 88 | 166 | 373 | 802 | 2,644 |
| | in lb | | 115 | 295 | 780 | 1,470 | 3,300 | 7,100 | 23,400 |
| | Nm | 10 | 26 | 66 | 169 | 333 | 734 | 1,582 | 3,277 |
| | in lb | | 230 | 580 | 1,500 | 2,950 | 6,500 | 14,000 | 29,000 |
| Emergency ⁽¹⁾ Stop Output Torque, $T_{em r}$ | Nm | 15-100 | 37 | 101 | 260 | 452 | 1,096 | 2,000 | 5,311 |
| | in lb | | 330 | 890 | 2,300 | 4,000 | 9,700 | 17,700 | 47,000 |
| | Nm | 5 | 31 | 77 | 203 | 384 | 870 | 1,853 | 6,102 |
| | in lb | | 270 | 680 | 1,800 | 3,400 | 7,700 | 16,400 | 54,000 |
| | Nm | 10 | 60 | 153 | 395 | 768 | 1,695 | 3,684 | 7,684 |
| | in lb | | 530 | 1,350 | 3,500 | 6,800 | 15,000 | 32,600 | 68,000 |
| Nominal Input Speed, $N_{nom r}$ | Nm | 15-100 | 87 | 232 | 599 | 1,040 | 2,520 | 4,588 | 12,316 |
| | in-lb | | 770 | 2,050 | 5,300 | 9,200 | 22,300 | 40,600 | 109,000 |
| | RPM | 5,10 | 3,200 | 2,800 | 2,400 | 2,000 | 1,600 | 1,200 | 1,000 |
| | RPM | 15-40 | 3,700 | 3,300 | 2,900 | 2,500 | 2,000 | 1,500 | 1,250 |
| Maximum Input Speed, $N_{max r}$ | RPM | 50-100 | 4,200 | 3,800 | 3,400 | 3,000 | 2,400 | 1,800 | 1,500 |
| | RPM | 5-100 | 6,000 | 5,300 | 4,500 | 3,800 | 3,000 | 2,300 | 1,900 |
| Standard Backlash ⁽²⁾ | arc min | 5,10 | 14 | 12 | 12 | 10 | 10 | 10 | 10 |
| | arc min | 15-100 | 12 | 10 | 10 | 8 | 8 | 8 | 8 |
| Low Backlash ⁽²⁾ | arc min | 5,10 | 10 | 8 | 8 | 6 | 6 | 6 | 6 |
| | arc min | 15-100 | 8 | 6 | 6 | 4 | 4 | 4 | 4 |
| Efficiency at Nominal Torque | % | | 94 | 94 | 94 | 94 | 94 | 94 | 94 |
| Noise Level ⁽³⁾ at: | | | | | | | | | |
| | 3,000 RPM | dB | 5-100 | 70 | 70 | 70 | — | — | — |
| | 2,000 RPM | dB | | — | — | — | 72 | 72 | — |
| 1,500 RPM | dB | | — | — | — | — | — | 72 | |
| Torsional Stiffness | Nm / arc min | 5-100 | 3 | 10 | 19 | 35 | 90 | 170 | 290 |
| | in lb / arc min | | 22 | 84 | 164 | 310 | 800 | 1,500 | 2,560 |
| Maximum Weight | kg | 5-100 | 2 | 6 | 11 | 24 | 43 | 80 | 120 |
| | lb | | 4 | 13 | 25 | 52 | 94 | 177 | 265 |
| Max. Allowable Case Temp. | °C | 5-100 | ← 100 → | | | | | | |

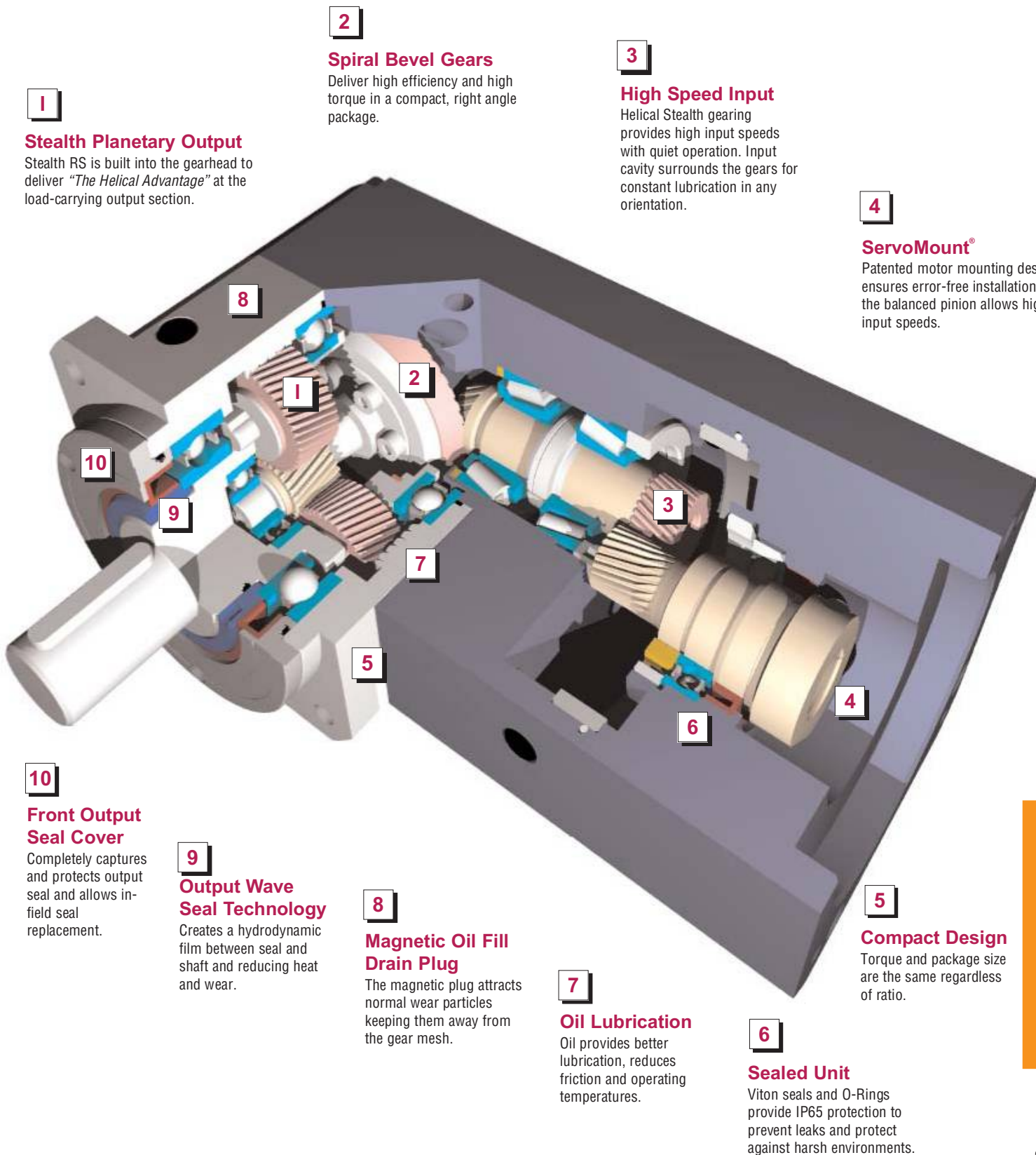
| Specifications: | Units | Ratio | Frame Size | | | | | | |
|----------------------------------|------------------------|----------|------------|-------|-------|-------|-------|-------|-------|
| | | | RS60 | RS90 | RS115 | RS142 | RS180 | RS220 | RS300 |
| Moment of Inertia ⁽⁴⁾ | g cm sec ² | 5 | 0.197 | 0.745 | 2.68 | 8.94 | 26.5 | 82.2 | 378 |
| | oz-in-sec ² | | 0.003 | 0.010 | 0.037 | 0.124 | 0.368 | 1.14 | 5.26 |
| | g cm sec ² | 10 | 0.095 | 0.489 | 1.67 | 5.87 | 16.7 | 50.4 | 238 |
| | oz-in-sec ² | | 0.001 | 0.007 | 0.023 | 0.082 | 0.232 | 0.700 | 3.31 |
| | g cm sec ² | 15,30 | 0.092 | 0.453 | 1.58 | 5.60 | 15.2 | 47.4 | 158 |
| | oz-in-sec ² | | 0.001 | 0.006 | 0.022 | 0.078 | 0.211 | 0.658 | 2.19 |
| | g cm sec ² | 20,25,40 | 0.083 | 0.358 | 1.13 | 4.17 | 10.7 | 34.3 | 116 |
| | oz-in-sec ² | | 0.001 | 0.005 | 0.016 | 0.058 | 0.149 | 0.476 | 1.61 |
| g cm sec ² | 50,100 | 0.072 | 0.238 | 0.685 | 2.26 | 6.70 | 21.2 | 95.4 | |
| oz-in-sec ² | | 0.001 | 0.003 | 0.010 | 0.031 | 0.093 | 0.294 | 1.32 | |

(1) Maximum of 1,000 stops
 (2) Measured at 2% of rated torque
 (3) Measured at 1 meter

(4) All Moment of Inertia values are as reflected at the input shaft of the gearhead.

(5) RS300 is available in Ratios of: 4, 6, 10, 15, 20, 24, 30 & 50:1
 Specification are subject to change without notice

Gearmotors & Gearheads



1

Stealth Planetary Output

Stealth RS is built into the gearhead to deliver "The Helical Advantage" at the load-carrying output section.

2

Spiral Bevel Gears

Deliver high efficiency and high torque in a compact, right angle package.

3

High Speed Input

Helical Stealth gearing provides high input speeds with quiet operation. Input cavity surrounds the gears for constant lubrication in any orientation.

4

ServoMount®

Patented motor mounting design ensures error-free installation and the balanced pinion allows higher input speeds.

10

Front Output Seal Cover

Completely captures and protects output seal and allows in-field seal replacement.

9

Output Wave Seal Technology

Creates a hydrodynamic film between seal and shaft and reducing heat and wear.

8

Magnetic Oil Fill Drain Plug

The magnetic plug attracts normal wear particles keeping them away from the gear mesh.

7

Oil Lubrication

Oil provides better lubrication, reduces friction and operating temperatures.

6

Sealed Unit

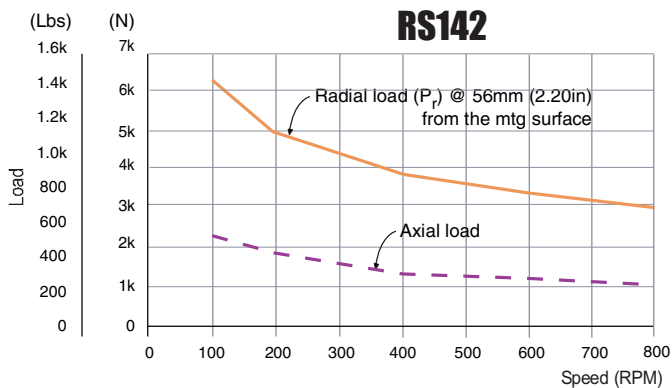
Viton seals and O-Rings provide IP65 protection to prevent leaks and protect against harsh environments.

5

Compact Design

Torque and package size are the same regardless of ratio.

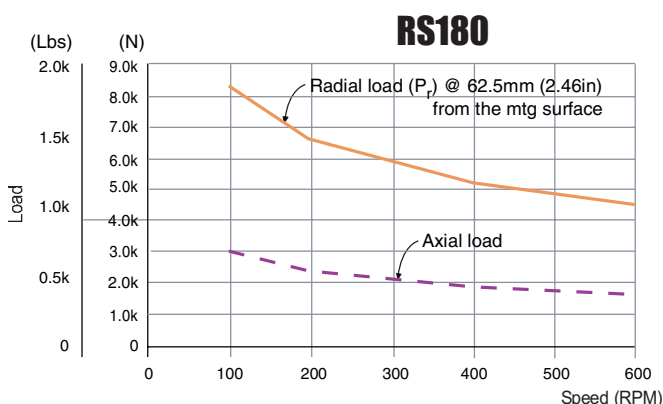
Gearmotors & Gearheads



Formulas to calculate Radial Load (P_{rx}) at any distance "X" from the gearhead mounting surface.

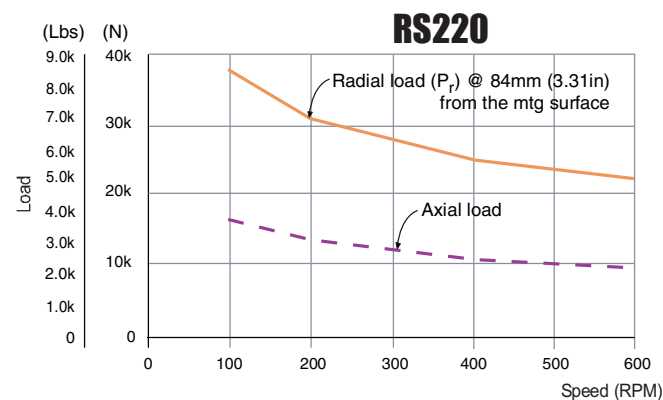
$$P_{rx} = (P_r)(127\text{mm}) / (71\text{mm} + X)$$

$$P_{rx} = (P_r)(5\text{in}) / (2.79\text{in} + X)$$



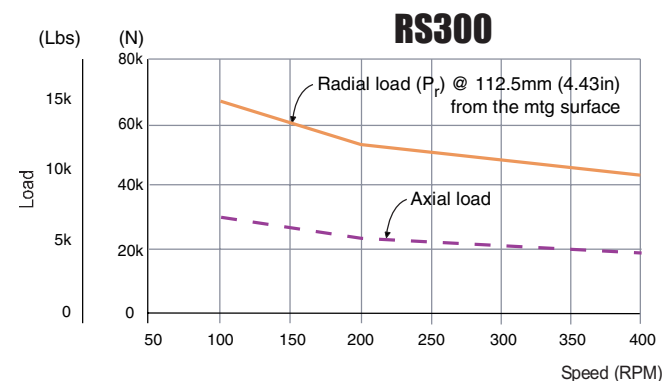
$$P_{rx} = (P_r)(138\text{mm}) / (76\text{mm} + X)$$

$$P_{rx} = (P_r)(5.43\text{in}) / (2.99\text{in} + X)$$



$$P_{rx} = (P_r)(190\text{mm}) / (106\text{mm} + X)$$

$$P_{rx} = (P_r)(7.48\text{in}) / (4.17\text{in} + X)$$

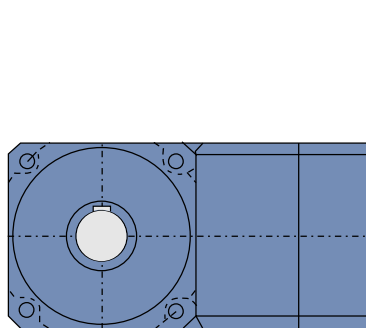


$$P_{rx} = (P_r)(268\text{mm}) / (156\text{mm} + X)$$

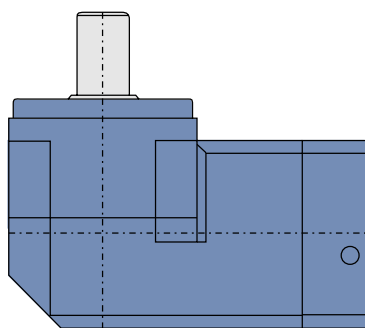
$$P_{rx} = (P_r)(10.55\text{in}) / (6.14\text{in} + X)$$

Gearmotors & Gearheads

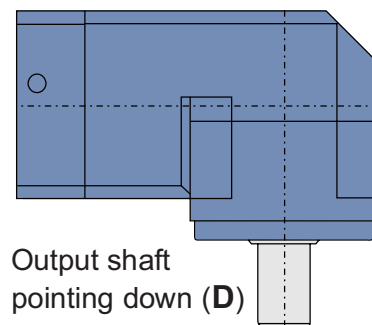
Stealth[®] RS Advanced Series: How to Order



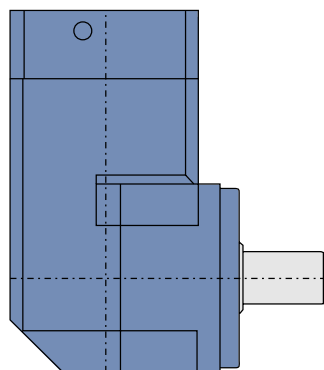
Horizontal orientation (H)



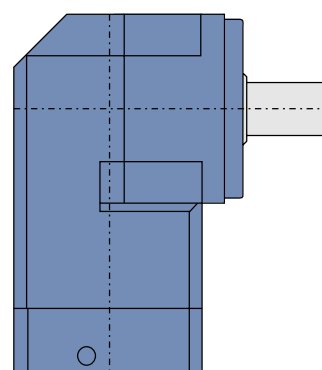
Output shaft pointing up (U)



Output shaft pointing down (D)



RS input facing up (E)



RS input facing down (F)

How to Order

Order Numbering Example:

R S 1 8 0 - 0 1 0 - X X X L H

1. Pick frame size and ratio.
2. Pick backlash and orientation.
3. Specify motor make and model for mounting

FRAME SIZE

60
90
115
142
180
220
300

RATIO

005 030
010 040
015 050
020 100
025

SPECIAL

(Factory Issued)

BACKLASH

L = Low backlash
S = Standard backlash

ORIENTATION

H = Horizontal orientation
U = Output shaft pointing up
D = Output shaft pointing down
E = RS input facing up
F = RS input facing down

(For other orientations consult the factory)

RS Gearheads are supported by a worldwide network of offices and local distributors. Call **1-800-305-4555** for application engineering assistance or for the name of your local distributor. Information can also be obtained at www.baysidemotion.com.

Gearmotors & Gearheads

Stealth[®] RX Series



Performance Specifications

| | Units | Ratio | Frame Size | | |
|--|---------------------|--------|-------------|-------------|--------------|
| | | | RX60 | RX90 | RX115 |
| Nominal Output Torque, $T_{nom r}$ | Nm | 5 | 7 | 17 | 45 |
| | in lb | | 58 | 149 | 484 |
| | Nm | 10 | 13 | 33 | 88 |
| | in lb | | 112 | 292 | 484 |
| | Nm | 15-25 | 20 | 51 | 129 |
| | in lb | | 175 | 451 | 1,238 |
| Max. Acceleration Output Torque, $T_{acc r}$ | Nm | 5 | 8 | 20 | 53 |
| | in lb | | 69 | 175 | 587 |
| | Nm | 10 | 16 | 40 | 101 |
| | in lb | | 138 | 350 | 1,140 |
| | Nm | 15-100 | 22 | 61 | 156 |
| | in lb | | 196 | 536 | 1,748 |
| Emergency ⁽¹⁾ Stop Output Torque, $T_{em r}$ | Nm | 5 | 19 | 46 | 122 |
| | in lb | | 165 | 409 | 1,362 |
| | Nm | 10 | 46 | 92 | 237 |
| | in lb | | 409 | 812 | 2,653 |
| | Nm | 15-100 | 67 | 139 | 359 |
| | in lb | | 594 | 1,232 | 4,022 |
| Nominal Input Speed, $N_{nom r}$ | RPM | 5, 10 | 3,200 | 2,800 | 2,400 |
| | RPM | 15-40 | 3,700 | 3,300 | 2,900 |
| | RPM | 50-100 | 4,200 | 3,800 | 3,400 |
| Maximum Input Speed, $N_{max r}$ | RPM | 5-100 | 6,000 | 5,300 | 4,500 |
| Standard Backlash ⁽²⁾ | arc min | 5, 10 | 20 | 18 | 18 |
| | arc min | 15-100 | 20 | 18 | 16 |
| Low Backlash ⁽²⁾ | arc min | 5, 10 | 18 | 16 | 16 |
| | arc min | 15-100 | 16 | 14 | 12 |
| Efficiency at Nominal Torque | % | 5-100 | 94 | 94 | 94 |
| Noise Level ⁽³⁾ at: 3,000 RPM | dB | 5-100 | 70 | 70 | 70 |
| Torsional Stiffness | Nm / arc min | 5-100 | 2.5 | 9.5 | 18.5 |
| | in lb / arc min | | 22 | 84 | 164 |
| Maximum Weight | kg | 5-100 | 2.01 | 5.74 | 11.35 |
| | lb | | 4.42 | 12.65 | 25 |
| Max. Allowable Case Temperature | °C | 5-100 | ← 100 → | | |

| Specifications: | Units | Ratio | Frame Size | | |
|----------------------------------|------------------------------|--------|---------------|---------------|---------------|
| | | | RX60 | RX90 | RX115 |
| Moment of Inertia ⁽⁴⁾ | gm cm sec² | 5 | 0.1970 | 0.7450 | 2.6820 |
| | oz in sec ² | | 0.0030 | 0.0100 | 0.0373 |
| | gm cm sec² | 10 | 0.0950 | 0.4890 | 1.6688 |
| | oz in sec ² | | 0.0013 | 0.0068 | 0.0232 |
| | gm cm sec² | 15, 30 | 0.0920 | 0.4530 | 1.5794 |
| | oz in sec ² | | 0.0013 | 0.0063 | 0.0219 |
| | gm cm sec² | 20-40 | 0.0830 | 0.3576 | 1.1324 |
| | oz in sec ² | | 0.0012 | 0.0050 | 0.0157 |
| | gm cm sec² | 50-100 | 0.0720 | 0.2384 | 0.6854 |
| | oz in sec ² | | 0.0010 | 0.0033 | 0.0095 |

(1) Maximum of 1,000 stops
(2) Measured at 2% of rated torque

(3) Measured at 1 meter
Specification are subject to change without notice

(4) All Moment of Inertia values are as reflected at the input